## Jury Theorem under Uncertainty

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## Merging

- Contradictory beliefs/goals coming from different sources
- Propositional Logic
- no priority (same reliability, hierarchical importance, ...)

- Base $K=$ a set of propositional formulae
- Profile $E=\left\{K_{1}, \ldots, K_{n}\right\}$
- Integrity Constraints = a propositional formula $\mu$
- Merging operator
$\triangle: E, \mu \longrightarrow K$


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K_{1} & K_{2} & K_{3} \\
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\triangle\left(\left\{K_{1}, K_{2}, K_{3}\right\}\right)= &
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## Merging vs Judgment Aggregation

Merging
A profile of belief bases

Judgment Aggregation
A profile of individual judgments

## Merging vs Judgment Aggregation

Merging
A profile of belief bases
Fully informed process

Judgment Aggregation
A profile of individual judgments
Partially informed process

## Merging vs Judgment Aggregation

|  | Merging | Judgment Aggregation |
| :--- | :--- | :--- |
| Input | A profile of belief bases | A profile of individual judgments |
| $\rightarrow$ | Fully informed process | Partially informed process |
| Computation | Global | Local |

## Merging vs Judgment Aggregation

Merging
A profile of belief bases
Fully informed process
Computation
Consequences - computational complexity + computational complexity

Judgment Aggregation
A profile of individual judgments
Partially informed process
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Merging
A profile of belief bases
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Computation
Consequences - computational complexity

+ logical properties - logical properties

Judgment Aggregation
A profile of individual judgments
Partially informed process
Local

+ computational complexity


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Merging
A profile of belief bases
Fully informed process
Computation
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+ logical properties
Ideal Process

Judgment Aggregation
A profile of individual judgments
Partially informed process
Local

+ computational complexity
- logical properties

Practical Process

## Definitions

- A base $\varphi$ is a (finite set of) propositional formula
- A profile $E$ is a multi-set of bases $E=\left\{\varphi_{1}, \ldots, \varphi_{n}\right\}$
- $\wedge E$ denotes the conjunction of the bases of $E$, i.e. $\wedge E=\varphi_{1} \wedge \ldots \wedge \varphi_{n}$
- A profile $E$ is consistent if and only if $\bigwedge E$ is consistent We will note $\operatorname{Mod}(E)$ the models of $\bigwedge E$
- Equivalence between profiles :
$\square$ Let $E_{1}, E_{2}$ be two profiles. $E_{1}$ and $E_{2}$ are equivalent, noted $E_{1} \equiv E_{2}$, iff there exists a bijection $f$ from $E_{1}=\left\{\varphi_{1}^{1}, \ldots, \varphi_{n}^{1}\right\}$ to $E_{2}=\left\{\varphi_{1}^{2}, \ldots, \varphi_{n}^{2}\right\}$ such that $\vdash f(\varphi) \leftrightarrow \varphi$.


## Belief Merging vs. Goal Merging

- Logical properties for merging
- Same properties for belief merging and goal merging
- Is it possible to discriminate these two tasks?


## Logical Properties

$\triangle$ is a merging with integrity constraints operator (IC merging operator) if it satisfies the following properties :
(ICO) $\triangle_{\mu}(E) \vdash \mu$
(IC1) If $\mu$ is consistent, then $\triangle_{\mu}(E)$ is consistent
(IC2) If $\wedge E$ is consistent with $\mu$, then $\triangle_{\mu}(E)=\wedge E \wedge \mu$
(IC3) If $E_{1} \equiv E_{2}$ and $\mu_{1} \equiv \mu_{2}$, then $\triangle_{\mu_{1}}\left(E_{1}\right) \equiv \triangle_{\mu_{2}}\left(E_{2}\right)$
(IC4) If $\varphi \vdash \mu$ and $\varphi^{\prime} \vdash \mu$, then $\triangle_{\mu}\left(\varphi \sqcup \varphi^{\prime}\right) \wedge \varphi \nvdash \perp \Rightarrow \triangle_{\mu}\left(\varphi \sqcup \varphi^{\prime}\right) \wedge \varphi^{\prime} \nvdash \perp$
(IC5) $\triangle_{\mu}\left(E_{1}\right) \wedge \triangle_{\mu}\left(E_{2}\right) \vdash \triangle_{\mu}\left(E_{1} \sqcup E_{2}\right)$
(IC6) If $\triangle_{\mu}\left(E_{1}\right) \wedge \triangle_{\mu}\left(E_{2}\right)$ is consistent, then $\triangle_{\mu}\left(E_{1} \sqcup E_{2}\right) \vdash \triangle_{\mu}\left(E_{1}\right) \wedge \triangle_{\mu}\left(E_{2}\right)$
(IC7) $\triangle_{\mu_{1}}(E) \wedge \mu_{2} \vdash \triangle_{\mu_{1} \wedge \mu_{2}}(E)$
(IC8) If $\triangle_{\mu_{1}}(E) \wedge \mu_{2}$ is consistent, then $\triangle_{\mu_{1} \wedge \mu_{2}}(E) \vdash \triangle_{\mu_{1}}(E)$

## Synthesis View vs. Epistemic View

- Synthesis view: define a base which best represents the input profile


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|  | beliefs | goals |
| :--- | :--- | :--- |
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- Condorcet's Jury Theorem [Condorcet 1785]


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- Condorcet's Jury Theorem [Condorcet 1785]
- Merging?


## Outline

- Condorcet's Jury Theorem
- Jury Theorem under Uncertainty
- Truth Tracking Postulate
- Some Experiments on Convergence Speed
- Conclusion


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- Suppose

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- $\omega^{\star}$ is the correct answer
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- independent
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Consider a real number $p^{\star} \in[0,1[$ and a profile $E$ from a set of $n$ independent agents who have the same reliability $p>p^{\star}$. The probability that the score of the correct answer exceeds $n p^{\star}$ tends to 1 when $n$ tends to infinity.

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P\left(s_{a}\left(\omega^{\star}\right)>n p^{\star}\right) \xrightarrow[n \rightarrow \infty]{ } 1
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Majority rule: $M(E)=\left\{\omega\right.$ s.t. $\left.s_{a}(\omega)>n \times 1 / 2\right\}$
$\kappa$-Quota rule: $Q_{\kappa}(E)=\left\{\omega\right.$ s.t. $\left.s_{a}(\omega)>n \times \kappa\right\} \quad(\kappa \in] 0,1[)$

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## Jury Theorem under Uncertainty II

- $k$ alternatives : $\left\{\omega^{\star}, \omega_{1}, \ldots, \omega_{k-1}\right\}$
- Uncertainty: each individual $i$ may vote for any subset $X_{i}$ of alternatives
- Reliability: probability $\left(p_{i}\right)$ than the correct answer is among the alternatives pointed out by the individual


## Proposition

Consider a real number $p^{\star} \in[0,1[$ and a profile $E$ from a set of $n$ independent agents who have the same reliability $p>p^{\star}$. The probability that the score of the correct answer exceeds $n p^{\star}$ tends to 1 when $n$ tends to infinity.

$$
P\left(s_{a}\left(\omega^{\star}\right)>n p^{\star}\right) \xrightarrow[n \rightarrow \infty]{ } 1
$$

$$
s_{a}(\omega)=\mid\left\{K_{i} \in E \text { s.t. } \omega \models K_{i}\right\} \mid
$$

Majority rule: $M(E)=\left\{\omega\right.$ s.t. $\left.s_{a}(\omega)>n \times 1 / 2\right\}$
$\kappa$-Quota rule: $Q_{\kappa}(E)=\left\{\omega\right.$ s.t. $\left.s_{a}(\omega)>n \times \kappa\right\} \quad(\kappa \in] 0,1[)$

- If all individuals share the same reliability $p>\kappa$, then the correct answer belongs to the set of states returned by the $\kappa$-quota rule in the limit.
- Problem: The rule which always returns the set of all alternatives $\left\{\omega^{\star}, \omega_{1}, \ldots, \omega_{k-1}\right\}$ achieves the same result !


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- Improved reliability: an individual is R4-reliable if it is more reliable than incompetent


## Jury Theorem under Uncertainty III

## Theorem

Let $\left\{\omega^{\star}, \omega_{1}, \ldots, \omega_{k-1}\right\}$ be a set of possible worlds and let $E$ be a profile from a set of $n$ independent, homogenous and R4-reliable individuals. Then the probability than the correct answer is identified (i.e., is the only chosen alternative) by the majority tends to 1 as the group size increases, i.e., $\forall i \in\{1, \ldots, k-1\}$,

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P\left(s_{a}\left(\omega^{\star}\right)>s_{a}\left(\omega_{i}\right)\right) \xrightarrow[n \rightarrow \infty]{ } 1
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- R4-reliability extends reliability in [LIST GOodin 2001] and [CONDORCET 1785]
- Jury Theorem under Uncertainty extends [List Goodin 2001] Theorem and Condorcet's Jury Theorem


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- R4-reliability extends reliability in [List Goodin 2001] and [CONDORCET 1785]
- Jury Theorem under Uncertainty extends [List Goodin 2001] Theorem and Condorcet's Jury Theorem
- The majority method in this Jury Theorem under Uncertainty is approval voting. Thus this theorem shows that approval voting is the appropriate truth-tracking method for voting on $k(k>2)$ alternatives


## Distance-based merging operators

- Let $d$ be a distance between interpretations and $f$ be an aggregation function. The merging operator $\triangle^{d, f}(E)$ is defined by:

$$
\bmod \left(\triangle_{\mu}^{d, f}(E)\right)=\min \left(\bmod (\mu), \leq_{E}\right)
$$

where the pre-order $\leq_{E}$ on $\mathcal{W}$ induced by $E$ is defined by:
$\square \omega \leq_{E} \omega^{\prime}$ if and only if $d(\omega, E) \leq d\left(\omega^{\prime}, E\right)$, where

- $d(\omega, E)=f_{K \in E}(d(\omega, K))$, where
- $d(\omega, K)=\min _{\omega^{\prime} \vDash K} d\left(\omega, \omega^{\prime}\right)$
- Examples of distances:
$\square$ drastic distance $d_{D}$
- Hamming (Dalal) distance $d_{H}$
- Examples of aggregation functions:
- sum ( $\Sigma$ )
- leximax (Gmax)
- leximin (Gmin)


## Truth Tracking Postulate for Merging Operators

Let $\triangle$ be a merging operator
(TT) Let $E$ be a profile from $n$ independent, homogeneous and R4-reliable agents. Let $\omega^{\star}$ be the real world.

$$
P\left([\triangle(E)]=\left\{\omega^{\star}\right\}\right) \underset{n \rightarrow \infty}{\longrightarrow} 1
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## Proposition

- $\triangle^{d_{H}, G m a x}$ does not satisfy (TT)


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Let $\triangle$ be a merging operator
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## Proposition

- $\triangle^{d_{H}, G m a x}$ does not satisfy (TT)
- $\triangle^{d_{H}, \Sigma}$ does not satisfy (TT)
- $\triangle^{d_{D}, \Sigma}$ satisfies (TT)
- For any pseudo-distance d, $\triangle^{d, G m i n}$ satisfies (TT)


## Some Experimental Results: Convergence Speed (7 variables, $\mathrm{p}=0.9$ )

- p: agents reliability $\left(p=P\left(\omega^{\star} \in K_{i}\right)\right)$
- q : agents incompetence $\left(q=P\left(\omega \neq \omega^{\star} \in K_{i}\right)\right)$

Probability of Success


## Some Experimental Results: Convergence Speed (7 variables, $\mathrm{p}=0.3$ )

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- q : agents incompetence $\left(q=P\left(\omega \neq \omega^{\star} \in K_{i}\right)\right)$
${ }_{100}$ Probability of success
Number of agenhts ${ }^{8}$ \%


## Conclusion, Related Work and Perspectives

- Conclusion
- Jury Theorem under Uncertainty
- Difference between belief merging and goal merging
- Synthesis view versus epistemic view of merging
- Truth tracking postulate
- Related Work
- Truth Tracking for Judgement Aggregation
[Bovens Rabinowicz 2006] [Pigozzi Hartmann 2007]
- Perspectives

■ Releasing assumptions (homogeneity, etc...)

- [Owen-Grofman-Feld 1989]:

The average reliability is greater than 0.5

- Judgment Aggregation methods and Maximum likelihood

