#### Jury Theorem under Uncertainty

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- Contradictory beliefs/goals coming from different sources
- Propositional Logic
- no priority (same reliability, hierarchical importance, ...)



- Base K = a set of propositional formulae
- Profile  $E = \{K_1, ..., K_n\}$
- Integrity Constraints = a propositional formula μ
- Merging operator  $\triangle: E, \mu \longrightarrow K$

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A profile of belief bases

Judgment Aggregation

A profile of individual judgments

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	Ideal Process	Practical Process

- A base  $\varphi$  is a (finite set of) propositional formula
- A profile *E* is a multi-set of bases  $E = \{\varphi_1, \dots, \varphi_n\}$
- $\bigwedge E$  denotes the conjunction of the bases of E, i.e.  $\bigwedge E = \varphi_1 \land \ldots \land \varphi_n$
- A profile *E* is consistent if and only if ∧ *E* is consistent We will note *Mod*(*E*) the models of ∧ *E*
- Equivalence between profiles :
  - Let  $E_1, E_2$  be two profiles.  $E_1$  and  $E_2$  are *equivalent*, noted  $E_1 \equiv E_2$ , iff there exists a bijection f from  $E_1 = \{\varphi_1^1, \ldots, \varphi_n^1\}$  to  $E_2 = \{\varphi_1^2, \ldots, \varphi_n^2\}$  such that  $\vdash f(\varphi) \leftrightarrow \varphi$ .

- Logical properties for merging
- Same properties for belief merging and goal merging
- Is it possible to discriminate these two tasks?

 $\bigtriangleup$  is a merging with integrity constraints operator (IC merging operator) if it satisfies the following properties :

(IC0)  $\triangle_{\mu}(E) \vdash \mu$ (IC1) If  $\mu$  is consistent, then  $\triangle_{\mu}(E)$  is consistent (IC2) If  $\bigwedge E$  is consistent with  $\mu$ , then  $\triangle_{\mu}(E) = \bigwedge E \land \mu$ (IC3) If  $E_1 \equiv E_2$  and  $\mu_1 \equiv \mu_2$ , then  $\triangle_{\mu_1}(E_1) \equiv \triangle_{\mu_2}(E_2)$ (IC4) If  $\varphi \vdash \mu$  and  $\varphi' \vdash \mu$ , then  $\triangle_{\mu}(\varphi \sqcup \varphi') \land \varphi \nvDash \bot \Rightarrow \triangle_{\mu}(\varphi \sqcup \varphi') \land \varphi' \nvDash \bot$ (IC5)  $\triangle_{\mu}(E_1) \land \triangle_{\mu}(E_2) \vdash \triangle_{\mu}(E_1 \sqcup E_2)$ (IC6) If  $\triangle_{\mu}(E_1) \land \triangle_{\mu}(E_2)$  is consistent, then  $\triangle_{\mu}(E_1 \sqcup E_2) \vdash \triangle_{\mu}(E_1) \land \triangle_{\mu}(E_2)$ (IC7)  $\triangle_{\mu_1}(E) \land \mu_2 \vdash \triangle_{\mu_1 \land \mu_2}(E)$ (IC8) If  $\triangle_{\mu_1}(E) \land \mu_2$  is consistent, then  $\triangle_{\mu_1 \land \mu_2}(E) \vdash \triangle_{\mu_1}(E)$ 

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- Merging?

- Condorcet's Jury Theorem
- Jury Theorem under Uncertainty
- Truth Tracking Postulate
- Some Experiments on Convergence Speed
- Conclusion

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## Condorcet's Jury Theorem

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Consider a real number  $p^* \in [0, 1[$  and a profile E from a set of n independent agents who have the same reliability  $p > p^*$ . The probability that the score of the correct answer exceeds  $np^*$  tends to 1 when n tends to infinity.

$$P(s_a(\omega^*) > np^*) \xrightarrow[n \to \infty]{} 1$$

$$s_a(\omega) = |\{K_i \in E \text{ s.t. } \omega \models K_i\}|$$

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 $\begin{array}{ll} \text{Majority rule: } \mathcal{M}(\mathcal{E}) = \{ \omega \text{ s.t. } s_a(\omega) > n \times 1/2 \} \\ \kappa \text{-Quota rule: } \mathcal{Q}_{\kappa}(\mathcal{E}) = \{ \omega \text{ s.t. } s_a(\omega) > n \times \kappa \} & (\kappa \in ]0,1[) \end{array}$ 

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- But how to consider an individual always reporting a large set of alternatives?
  - An individual who always chooses all the alternatives is perfectly reliable
  - An individual is interesting (from a jury point of view) if she points out few alternatives
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- Improved reliability: an individual is R4-reliable if it is more reliable than incompetent

#### Theorem

Let  $\{\omega^*, \omega_1, \ldots, \omega_{k-1}\}$  be a set of possible worlds and let E be a profile from a set of n independent, homogenous and R4-reliable individuals. Then the probability than the correct answer is identified (i.e., is the only chosen alternative) by the majority tends to 1 as the group size increases, i.e.,  $\forall i \in \{1, \ldots, k-1\},\$ 

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- R4-reliability extends reliability in [LIST GOODIN 2001] and [CONDORCET 1785]
- Jury Theorem under Uncertainty extends [LIST GOODIN 2001] Theorem and Condorcet's Jury Theorem

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- R4-reliability extends reliability in [LIST GOODIN 2001] and [CONDORCET 1785]
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- The majority method in this Jury Theorem under Uncertainty is approval voting. Thus this theorem shows that approval voting is the appropriate truth-tracking method for voting on k (k > 2) alternatives

## Distance-based merging operators

 Let *d* be a distance between interpretations and *f* be an aggregation function. The merging operator △<sup>d,f</sup>(*E*) is defined by:

$$mod(\triangle_{\mu}^{d,f}(E)) = min(mod(\mu), \leq_E)$$

where the pre-order  $\leq_E$  on W induced by E is defined by:

- $\omega \leq_E \omega'$  if and only if  $d(\omega, E) \leq d(\omega', E)$ , where
- $d(\omega, E) = f_{K \in E}(d(\omega, K))$ , where
- $d(\omega, K) = \min_{\omega' \models K} d(\omega, \omega')$
- Examples of distances:
  - drastic distance d<sub>D</sub>
  - Hamming (Dalal) distance d<sub>H</sub>
- Examples of aggregation functions:
  - sum (Σ)
  - leximax (Gmax)
  - Ieximin (Gmin)

Let riangle be a merging operator

**(TT)** Let *E* be a profile from *n* independent, homogeneous and R4-reliable agents. Let  $\omega^*$  be the real world.

$$P([\triangle(E)] = \{\omega^*\}) \xrightarrow[n \to \infty]{} 1$$
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•  $\triangle^{d_H, Gmax}$  does not satisfy **(TT)** 

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## Proposition

- $\triangle^{d_H,Gmax}$  does not satisfy **(TT)**
- Δ<sup>d<sub>H</sub>,Σ</sup> does not satisfy (TT)
- △<sup>d<sub>D</sub>,Σ</sup> satisfies (TT)
- For any pseudo-distance d, △<sup>d,Gmin</sup> satisfies (TT)

# Some Experimental Results: Convergence Speed (7 variables, p=0.9)

- p: agents reliability ( $p = P(\omega^* \in K_i)$ )
- q: agents incompetence ( $q = P(\omega \neq \omega^* \in K_i)$ )



# Some Experimental Results: Convergence Speed (7 variables, p=0.3)

- p: agents reliability ( $p = P(\omega^* \in K_i)$ )
- q: agents incompetence ( $q = P(\omega \neq \omega^* \in K_i)$ )



- Conclusion
  - Jury Theorem under Uncertainty
  - Difference between belief merging and goal merging
  - Synthesis view versus epistemic view of merging
  - Truth tracking postulate
- Related Work
  - Truth Tracking for Judgement Aggregation [Bovens Rabinowicz 2006] [Pigozzi Hartmann 2007]
- Perspectives
  - Releasing assumptions (homogeneity, etc...)
    - [OWEN-GROFMAN-FELD 1989]:

The average reliability is greater than 0.5

Judgment Aggregation methods and Maximum likelihood